## EVINRUDE<sup>®</sup> E-TEC<sup>®</sup> G2<sup>®</sup> **250 HP**

## SPECIFICATIONS

Engine Type	V6 74° E-TEC G2 D.I.			
Bore x Stroke - in (mm)	3.85 x 3.00 (98 x 76)			
Displacement - cu in (L)	210 (3.4L)			
Gear Ratio	1.85:1			
Full Throttle RPM Range	5400-6000 RPM			
Starting	Electric			
Controls	ICON II			
Fuel Induction	E-TEC Direct Injection with stratified low RPM combustion mode			
Alternator Output*	133 Amps Total / 50 net Dedicated / 14 amps @ idle			
Trim Method	Power Trim & Tilt			
Trim Range	-6° to 15°			
Tilt Range	81°			
Lubrication	Multi-Point Targeted Oiling			
Oil Tank Capacity - gal (L)	On-Engine 2 (7.5) / Accessory 1.8 (6.8), 3 (11.3) & 10 (37.85)			
Recommended Oil	XPS Marine XD100			
Recommended Fuel	87 Octane			
Warranty	5-Year Engine** / 5-Year Corrosion			
Mounting Centers - in (mm)	Minimum 28 (711)			
Color Customization	Over 400 Color Panel Options			
Steering Angle	+/- 30°			
Integrated Features	Dual Axis Rigging / iTrim			
100% Global Emissions Compliant	EPA 2013 / CARB 3 STAR / European Union			



INSTALLATION	COLOR	SHAFT LENGTH - in. (mm)	STEERING	MODEL NO.	WEIGHT - Ib (kg)
Single <sup>†</sup> / Multiple	Slate Gray	25 (635)	iSteer DPS IHS / Tiebar	H250GXF <sup>†</sup> H250GXC <sup>‡</sup>	558 (253) 558 (253)
		25 (635)	iSteer DPS IHS / Tiebar	H250WXF <sup>†</sup> H250WXC <sup>‡</sup>	558 (253) 558 (253)
			Optimus 360 / IHS IHS / Tiebar	H250WXI H250WXC‡	558 (253) 558 (253)
	Classic White	30 (762)	iSteer DPS IHS / Tiebar	H250WZF <sup>†</sup> H250WZC <sup>‡</sup>	570 (259) 570 (259)
			Optimus 360 / IHS IHS / Tiebar	H250WZI H250WZC <sup>‡</sup>	570 (259) 570 (259)

\* Variable Voltage Computer Controlled 133 Amp. Current amp calculated at 13.5 V. Net dedicated battery charging power output is 50 Amp.
\*\* 3 years of BRP Limited Warranty and 2 years of BRP Extended Service Terms B.E.S.T.

Specifications subject to change.

- † Standard Rotation iSteer DPS model available for single and multiple installation. All iDOCK and Optimus 360 models available for multiple installation only. ‡ Corresponding Counter Rotation model.
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